



autoMated vessels and supply chain
Optimisation for sustainable short
SEa Shipping



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## Facts about the MOSES project

Duration: 01.07.2020 - 30.06.2023
 (36 months) - extension
 31.12.2023 (42 months)

o Budget: 8 million €

Consortium: 17 Partners

Coordinator: NTUA







### MOSES aims to...





Containerised cargo







Create sustainable feeder services from large container terminals to small ports with no infrastructure to replace trucks on Ro-Ro ships





## The MOSES concept







### The MOSES Use Cases Northern Case France Romania Bosnia and Herzegovina Serbia Варна **Western MED-Spain** Bulgaria Decongest truck transport traffic in Valencia port and connect it to **Eastern MED-Greece** Sagunto and Gandia satellite ports Decongest Piraeus container terminal and integrate small Greek ports into the container supply chain Gibraltar Malta

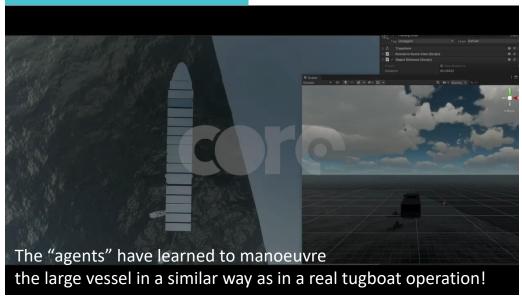
Tunisia



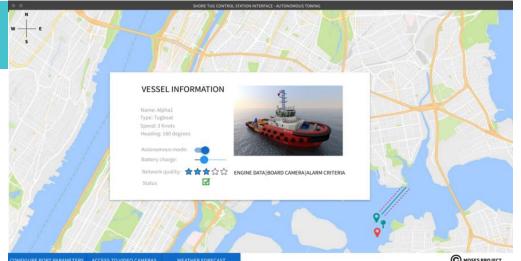


### MOSES AutoDock System

### **Autonomous tugboats**



**Shore Tugboat Control Station** 





#### **Automated Mooring**



#### Prototype innovations:

- Small-scale
- Surge motion control
- Energy harvesting
- Communication with tugboats









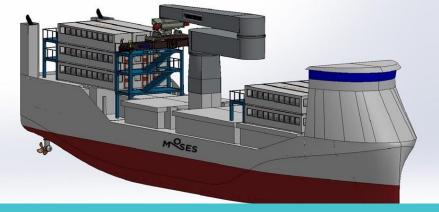
### **MOSES Innovative Feeder**

Greek concept I

L<sub>BP</sub> = 80 m180 TEU

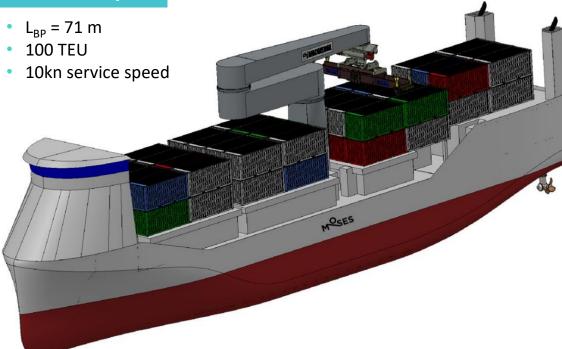
10 kn service speed





**Modular concept design** for pax transport





#### **Innovations**:

- Sustainable propulsion (Hybrid methanol ICE + batteries, Full electric)
- Azimuth thrusters for enhanced manoeuvrability
- Automated cargo-handling, as first step towards higher autonomy





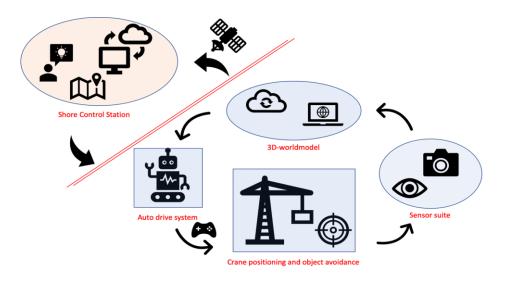
## **MOSES Robotic Cargo Handling System**



#### **Automated Crane**

- Compensation of pendulation (ship motions, weather conditions)
- Identification of container to load

#### **Intelligent Operator Support System (IOSS)**



- Enabling local situation awareness anomaly detection
- Robot self awareness in problem detection
- Control Intelligence
- Dynamic task allocation (One-to-many)
- Risk assessment for problem solving

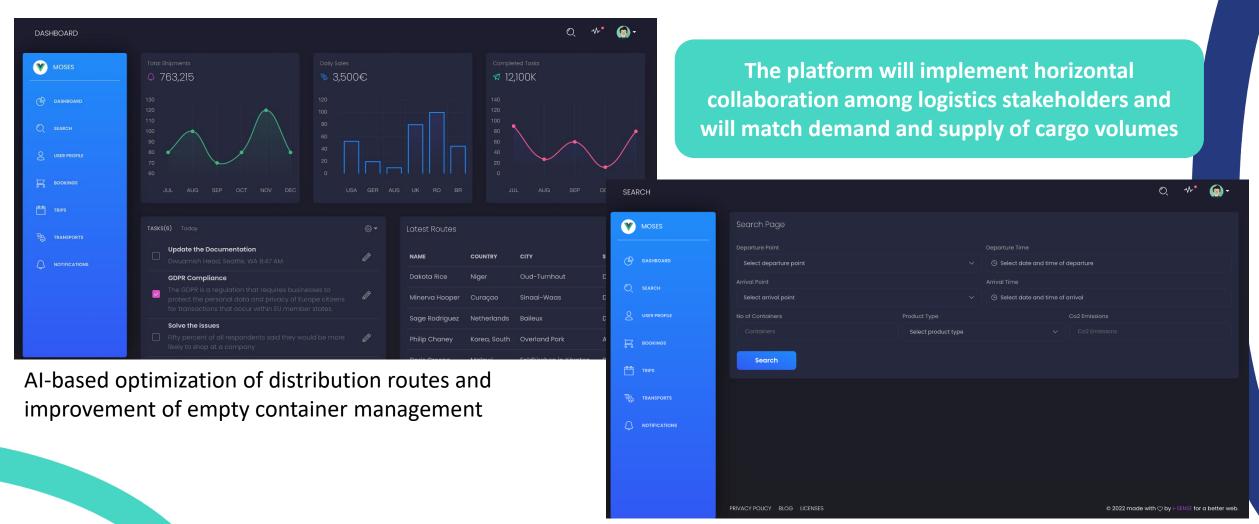






### **MOSES Matchmaking Platform**









## Pilot Demonstrations – Proof of Concepts



#### Pilot demonstration #1

- Autonomous "tugboat swarm" and automated docking
- Denmark



#### Pilot demonstration #2

- Dock-to-dock, fully autonomous operation of the MOSES feeder
- Netherlands

#### **Pilot demonstration #3**

- Autonomous operation of the Robotic Container-Handling System and remote monitoring with the IOSS
- Sweden, Netherlands







### Pilot Demonstration results



- The pilot demonstration results will provide input to the sustainability framework developed by MOSES
- The objective is to evaluate the sustainability and added value to SSS of the MOSES Innovations, based on specific criteria (incl. cost, environment, safety etc.)



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## **MOSES Exploitation Workshops**







Exploitation workshop on



AutoDock System



01 December 2023





Online, via Zoom platform



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**MOSES Project** 



# Thank you for your attention!

If you have any questions or require further information, please contact me:

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