

Exploitation workshop on



the autonomous sailing of MOSES Innovative Container Feeder Vessel



02 November 2023



10.00-12.00 CET



Online, via Zoom platform







10.00-12.00	Agenda items	
10.00-10.10	- Welcome /Opening session	Moderator
10.10-10.20	- MOSES Project at a glance	NTUA
10.20-10.50	- MOSES Pilot 2: "Autonomous Operation of the MOSES Innovative Feeder Vessel"- Outcomes and demo	MARIN
10.50-11.20	- Open Discussion	All
11.20-11.40	- MOSES exploitation perspective	CIRCLE
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11.50-12.00	- Wrap up & closing remarks	Moderator
	End of Day	







How can MOSES sustain a roadmap for post-project exploitation?

- Show the "proof of concept" results
- Identify opportunities and challenges for exploitation
- Connect to and get feedback from relevant stakeholders











autoMated vessels and supply chain Optimisation for sustainable short SEa Shipping



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Researcher, PhD Candidate,
School of Naval Architecture & Marine Engineering

National Technical University of Athens

Facts about the MOSES project

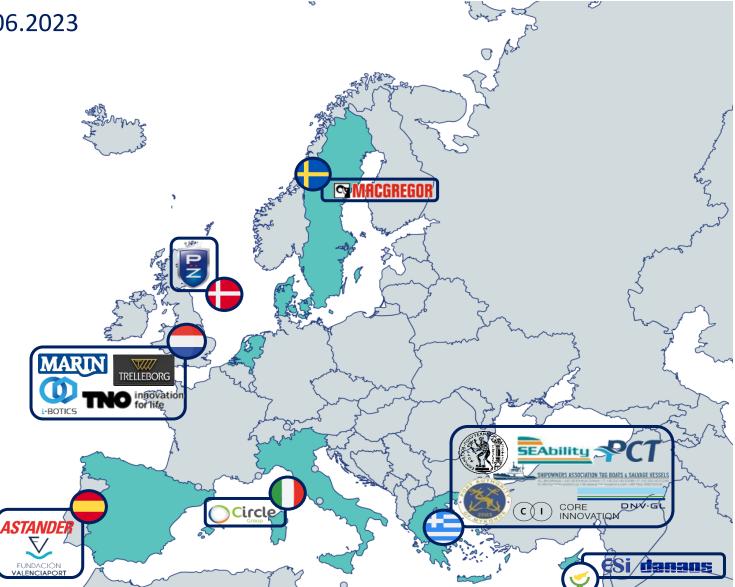
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Duration: 01.07.2020 - 30.06.2023
 (36 months) - extension
 31.12.2023 (42 months)

o Budget: 8 million €

Consortium: 17 Partners

Coordinator: NTUA







MOSES aims to...





Containerised cargo







Create sustainable feeder services from large container terminals to small ports with no infrastructure to replace trucks on Ro-Ro ships





The MOSES concept







The MOSES Use Cases Northern Case France Romania Bosnia and Herzegovina Serbia Варна **Western MED-Spain** Bulgaria Decongest truck transport traffic in Valencia port and connect it to **Eastern MED-Greece** Sagunto and Gandia satellite ports Decongest Piraeus container terminal and integrate small Greek ports into the container supply chain

Tunisia

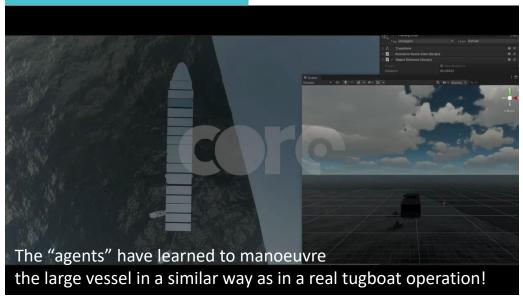
Malta



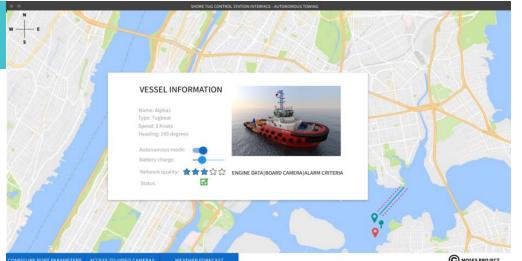


MOSES AutoDock System

Autonomous tugboats



Shore Tugboat Control Station





Automated Mooring



Prototype innovations:

- Small-scale
- Surge motion control
- Energy harvesting
- Communication with tugboats



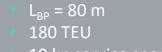


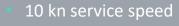




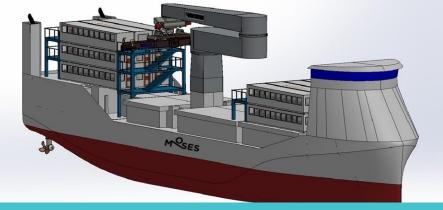
MOSES Innovative Feeder

Greek concept I



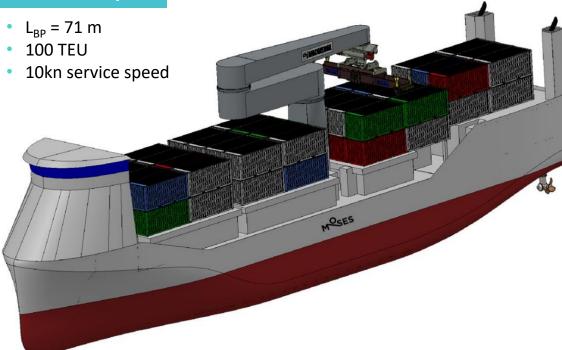






Modular concept design for pax transport





Innovations:

- Sustainable propulsion (Hybrid methanol ICE + batteries, Full electric)
- Azimuth thrusters for enhanced manoeuvrability
- Automated cargo-handling, as first step towards higher autonomy





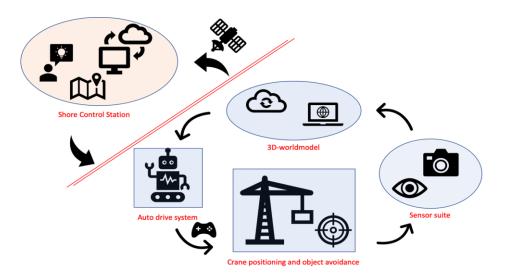
MOSES Robotic Cargo Handling System



Automated Crane

- Compensation of pendulation (ship motions, weather conditions)
- Identification of container to load

Intelligent Operator Support System (IOSS)



- Enabling local situation awareness anomaly detection
- Robot self awareness in problem detection
- Control Intelligence
- Dynamic task allocation (One-to-many)
- Risk assessment for problem solving

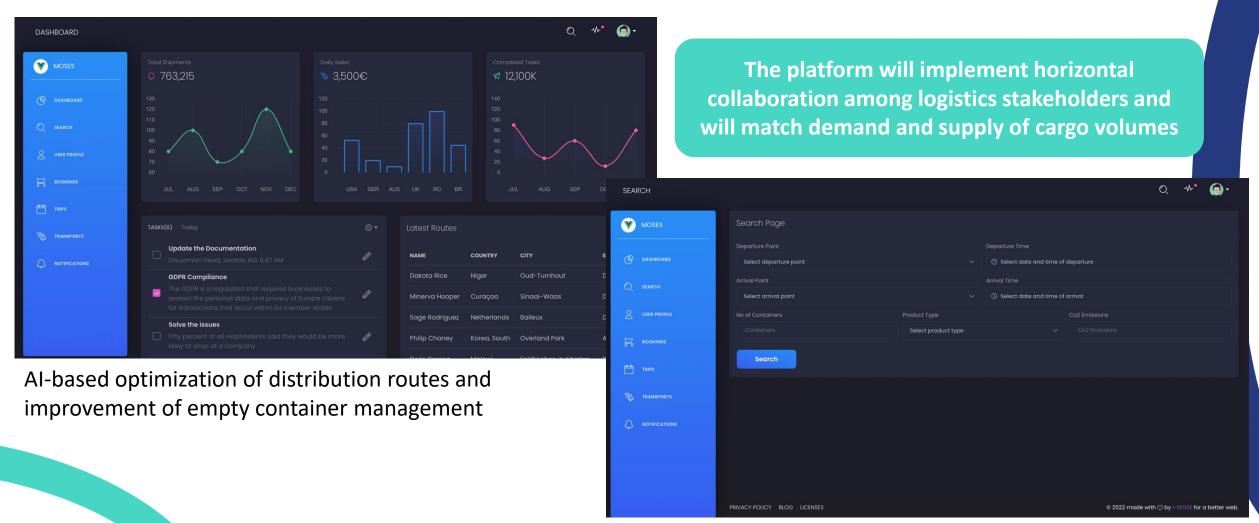






MOSES Matchmaking Platform









Pilot Demonstrations – Proof of Concepts



Pilot demonstration #1

- Autonomous "tugboat swarm" and automated docking
- **P** Denmark



Pilot demonstration #2

- Dock-to-dock, fully autonomous operation of the MOSES feeder
- Netherlands

Pilot demonstration #3

- Autonomous operation of the Robotic Container-Handling System and remote monitoring with the IOSS
- Sweden, Netherlands





28 Sep 2023

Pilot Demonstration results



- The pilot demonstration results will provide input to the sustainability framework developed by MOSES
- The objective is to evaluate the sustainability and added value to SSS of the MOSES Innovations, based on specific criteria (incl. cost, environment, safety etc.)



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MOSES Exploitation Workshops







Exploitation workshop on



Robotic Container Handling System



15 November 2023





Online, via Zoom platform



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One more thing...an interesting event













www. moses-h2020.eu



MOSES project2020



@mosesproject20



MOSES Project



Thank you for your attention!

If you have any questions or require further information, please contact me:

Konstantinos Louzis (klouzis@mail.ntua.gr)

National and Technical University of Athens - NTUA







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The workshop will be followed-up by sharing the insights and key results with all participants



